

# Omron TM Collaborative Robots



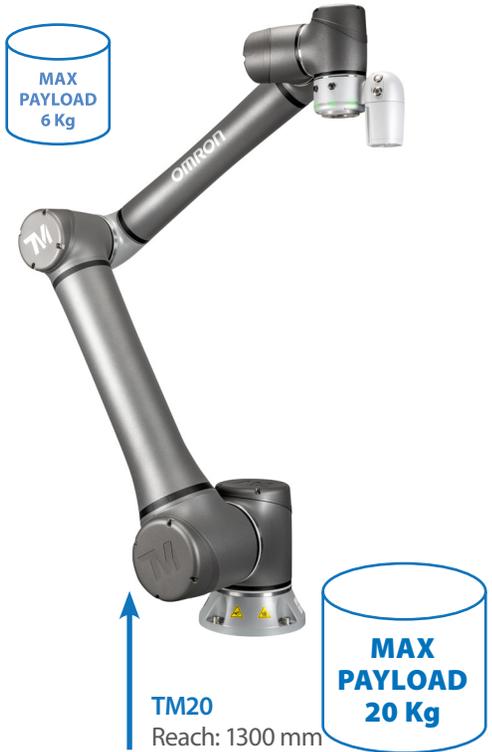
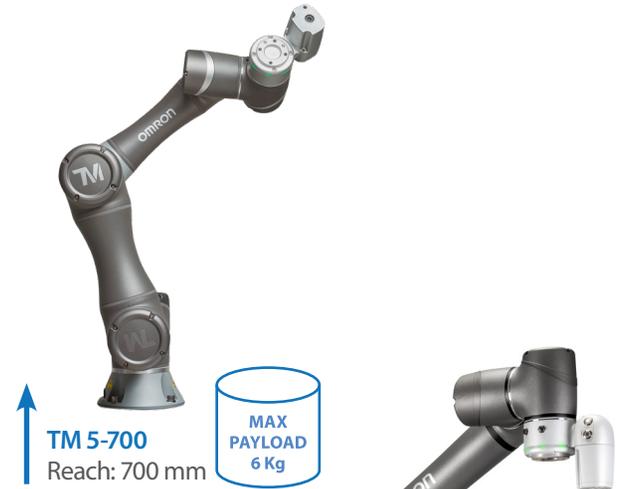
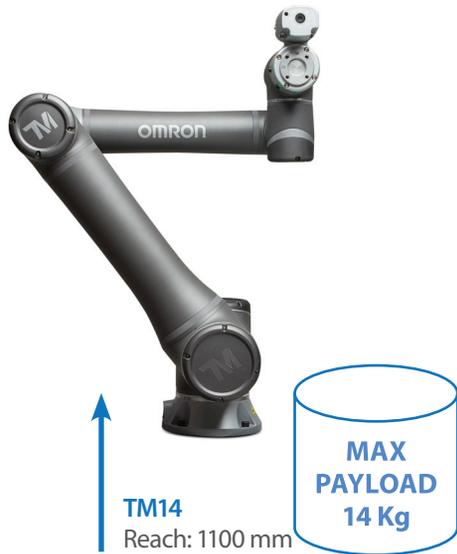
**OMRON**

# Omron TM Collaborative Robots

Omron's lineup of collaborative robots includes a variety of models to guarantee the right reach and payload capacity for different applications, including mobile robot-compatible (DC) versions.



Designed to meet safety regulations ISO 10218-1 (including TS 15066) and ISO 13849-1.



# Omron TM Collaborative Robots

The Omron TM Collaborative Robot is available in a variety of special models suited for specific applications and operational environments:

## SEMI-S2 Rated

Designed for semiconductor manufacturing and material handling to ensure the safety of the equipment.

## Integrated Fieldbus

Enabled for EtherNet/IP or PROFINET communication

## Mobile (DC) Power Supply

Includes a 22-60 VDC power supply to enable the integration with mobile robots for fully autonomous machine tending and logistics handling applications

## Food-Grade Grease

Features H1 rated grease sealed in the actuators allows the Omron TM Cobot installation in environments with incidental food contamination risk



Mobile (DC) Power Supply  
Omron TM Cobot mounted  
on a Mobile Robot



Food Grade Grease  
Omron TM Cobot

# Key industries and applications

Omron TM Collaborative Robots are designed for a wide variety of applications in a number of industries.

## Key Industries

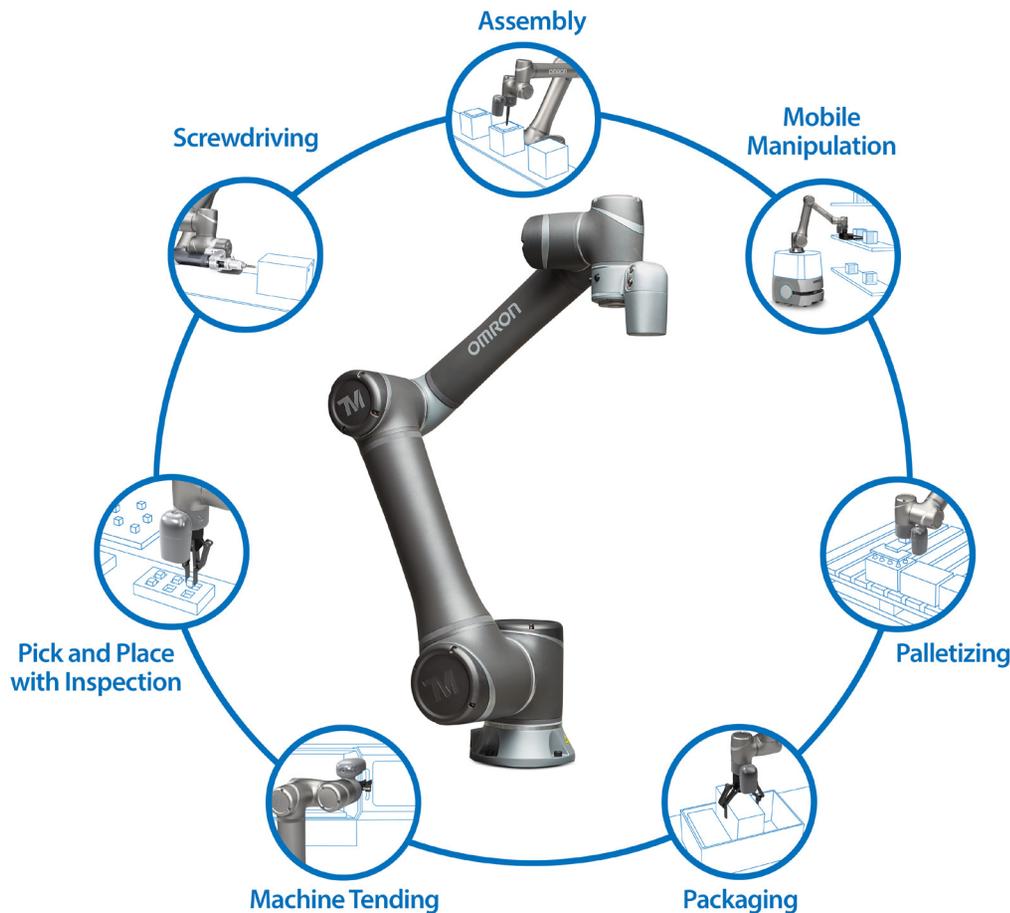
Automotive



Food & Commodities



Digital & Semiconductor



### Assembly:

Our cobots can improve throughput and consistency of repetitive or complex assembly tasks including part joining, insertion, tool changing, and working alongside people.

### Mobile Manipulation:

Mounting an Omron TM cobot onto an Omron LD mobile robot automates not only materials transport, but also complicated picking operations.

### Palletizing:

Our space-saving cobots can streamline end-of-line case stacking onto a pallet. With built-in vision, cases can be sorted by barcode or other visual indication.

### Packaging:

Our cobots can inspect and sort products, before putting them into cases. Customers can quickly adapt production lines to new products or seasonal models.

### Machine Tending:

A cobot can be used to tend CNC machines, injection molding machines, stamping and punch pressers, grinding, and cutting machines, relieving workers from repetitive and dangerous work.

### Pick and Place with Inspection:

Our cobots feature a built-in vision system that allows for easy pick-and-place together with sophisticated inspection, without the need for installing additional cameras or lighting equipment.

### Screwdriving:

Our cobots add precision and consistency to your screwdriving and parts fastening applications. A complete ready-to-use solution is provided with a screwdriving kit and pneumatic control box.

# Easy to use

With graphical programming, hand guidance, and intelligent vision, Omron TM cobots are designed to be easy and intuitive. Customers can set up simple applications in just a few minutes.

## Hand Guidance

Hand guidance mode allows users to easily set points and assign tasks to the robot. With buttons built into the cobot arm, users can guide the robot into position and automatically record the position in the software.

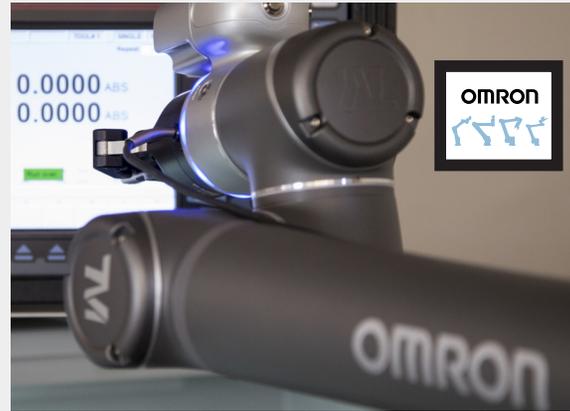


## ISO/TS 15066 Oriented Safety Settings

Our unique patented "body region safety settings" have preset safety parameter values, based on TS 15066 and robot kinematics. There is no need to understand complicated safety calculations to set up a safe application.

## Intelligent Vision

Our built-in vision system allows for quick setup of pick-and-place tasks, with the help of easy hand guiding and landmark positioning.

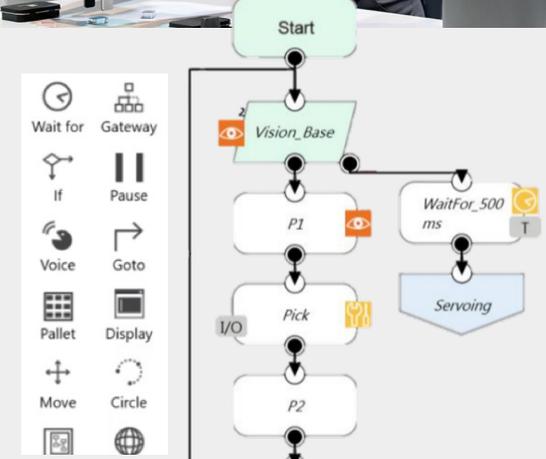


## Landmark

A landmark is a physical object that can be recognized by the robot's built-in camera, and acts as a beacon to help the robot navigate. The robot uses a Landmark as a reference point so it can better locate objects within the workspace. During high-mix, low-volume production with quick changeovers, customers can redeploy the robot without spending time to recalibrate the vision system.

## Graphical Programming

Intuitive programming allows users to automate a task with flow-based software, creating full workflows with a click-and-drag method.



# Designed for flexible manufacturing

Omron TM Collaborative Robots are designed to be easily redeployed to different tasks and applications, making production as flexible as needed.

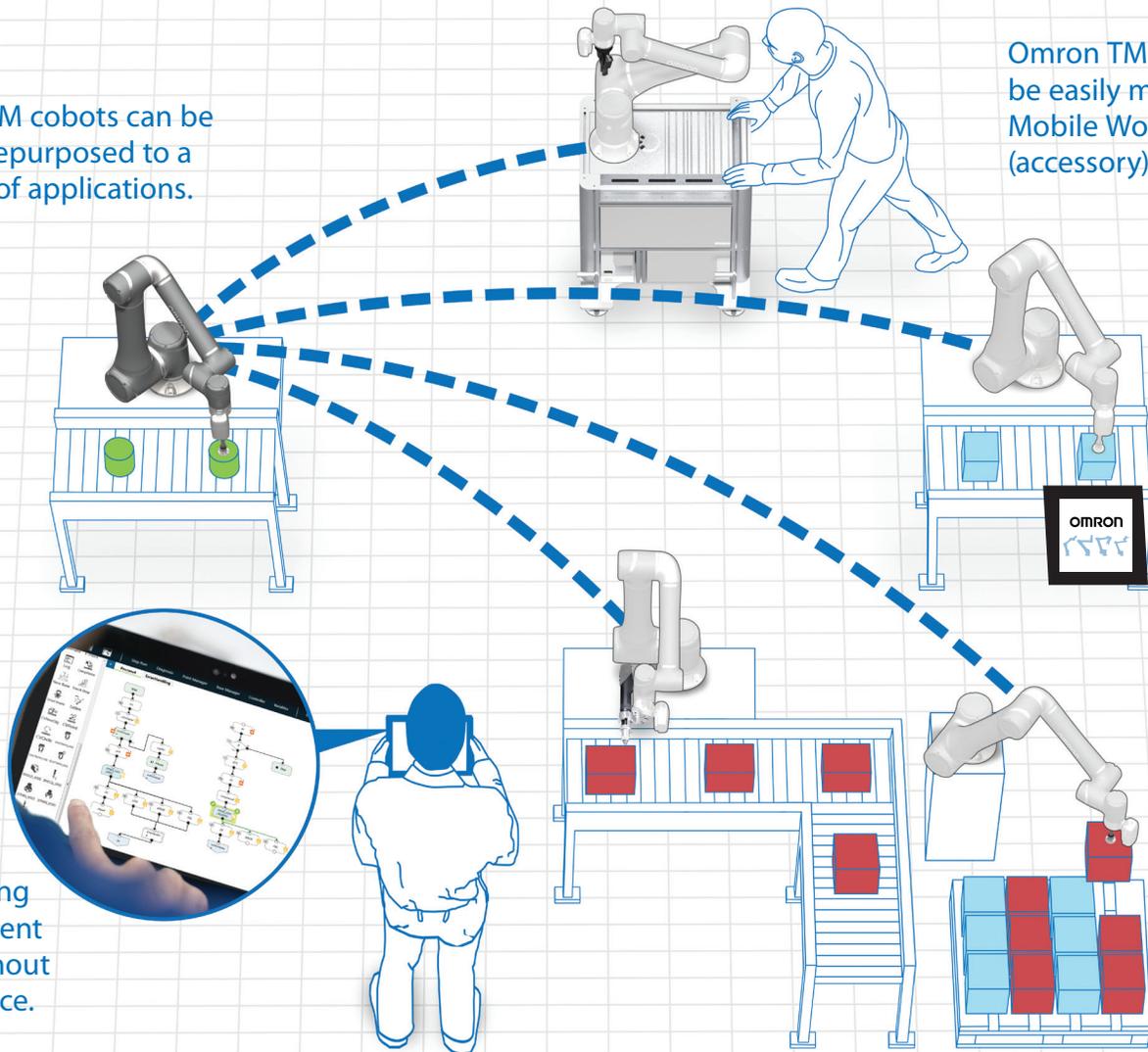
Omron TM cobots can be quickly repurposed to a number of applications.

Omron TM cobots can be easily moved on the Mobile Workstation (accessory).

The built-in vision system uses Landmarks that help the cobot navigate without the need for fixed jigs.

Graphical programming allows quick deployment and changeovers without prior coding experience.

Omron TM Collaborative Robots can fit into small spaces, even inverted or at any angle, making them adaptable to almost any factory environment.



# Built-In Vision

Users can set up vision tasks for immediate deployment without going through complex steps of integrating external cameras or lighting equipment. For even greater utility, users can choose to add up to two optional external cameras to best suit their unique application needs.



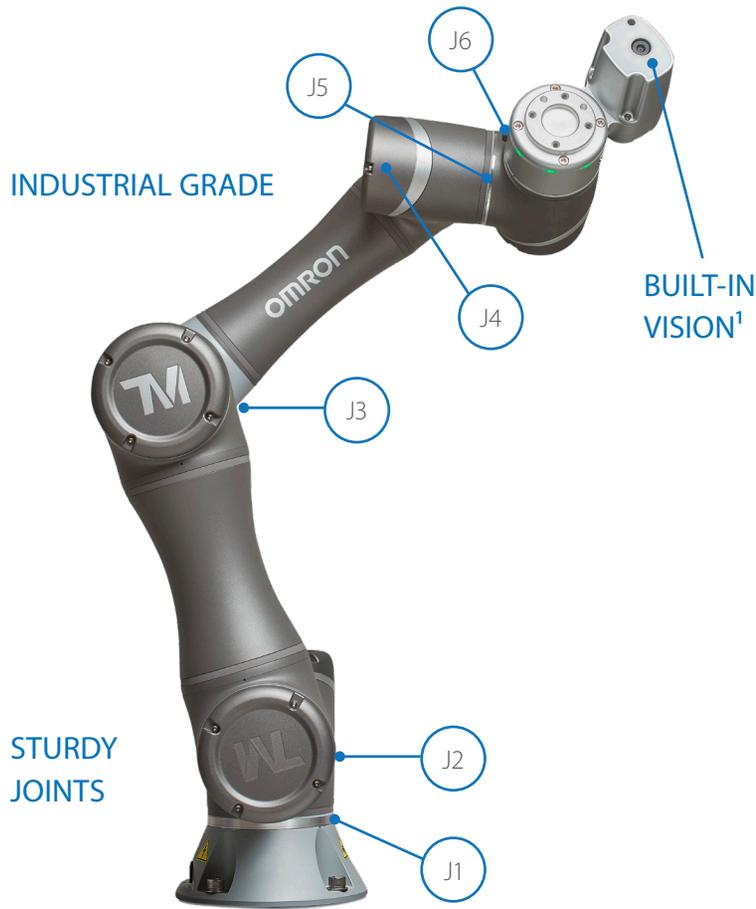
## Standard Vision Package

	Contrast Enhancement		Pattern Matching (Shape)		Barcode QR Code
	Color Plane Extraction		Pattern Matching (Image)		Color Classifier
	Smoothing		Blob Finder		String match
	Thresholding		Anchor		
	Morphology		Fiducial Mark Matching		
	Flip				

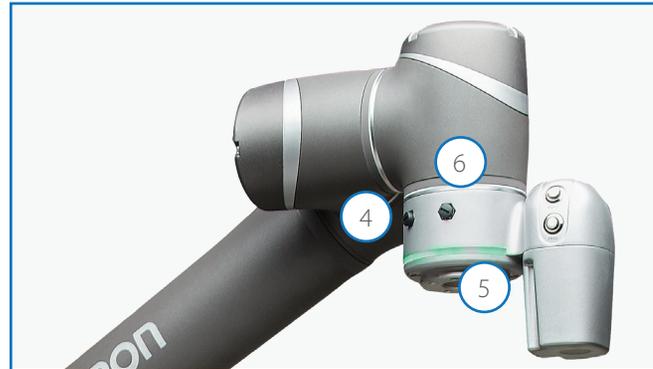
## Optional Vision Package

	Pose Variation (Shape)		Counting (Blobs)		Line Burr		Gauge (Distance & Angle)
	Pose Variation (Image)		Counting (Shape)		Circle Burr		OCR (Number)
	Specific Color Area Size		Counting (Image)		OCR (Letter)		
	Subtract Reference Image		Counting (Edges)				

# Anatomy of an Omron TM Cobot



1. VISION button teaches vision tasks and task sequences
2. POINT button records position in cobot program
3. FREE button allows hands-on teaching



4. Analog I/O port
5. Indicator light ring shows robot status
6. Digital I/O port



7. Built-in camera with integrated light
8. Gripper button
9. End-of-arm tooling flange

1. No-camera version is available on request.

# Plug & Play

Omron has partnered with a select number of companies to offer a wide variety of peripherals that quickly and easily integrate with our cobots, allowing for a faster deployment and return on investment. They are collectively referred to as Plug & Play devices and software, designed to serve a broad range of customer applications and meet the highest testing standards of Omron.

## Plug & Play Categories

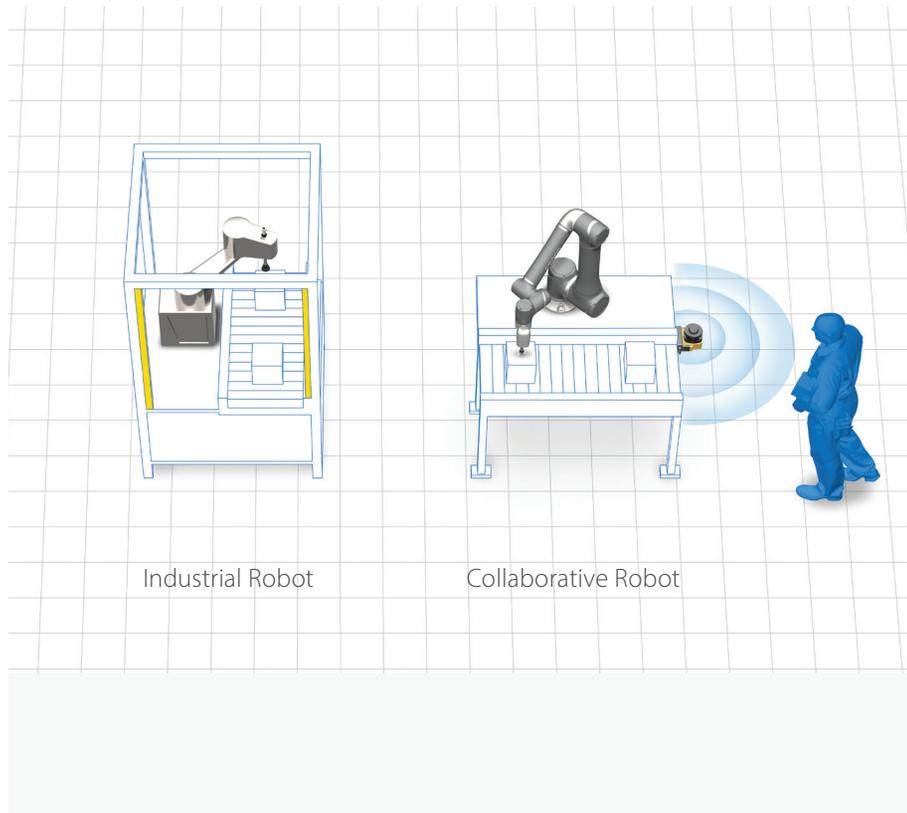


### Plug & Play Kits

All products come as a ready-to-use kit for easy installation.

# Choosing Cobots vs. Industrial Robot

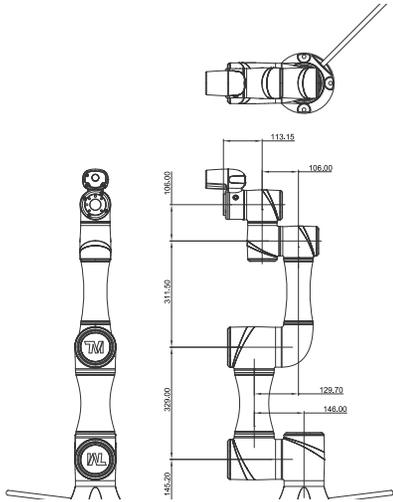
Collaborative Robots have changed the way the traditional factory used to work. Designed to “collaborate” with people, cobots offer users a safe and easy to use feature set that can eliminate physical cages as well as the need for highly trained robot programmers.



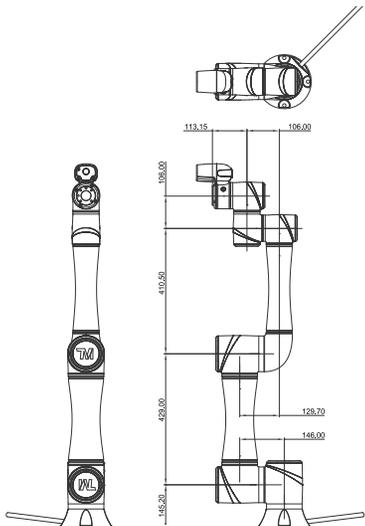
	Traditional Industrial Robots	Omron Cobots
<b>Safety</b>	Needs a physical barrier, such as a fence or cage, to ensure safety.	Designed to be inherently safe but may need safety sensors to ensure that the application is safe (e.g. Omron safety laser scanner) based on risk assessment. Typically does not need physical barrier if working in collaborative mode. Software safety setting is easy with graphical user interface.
<b>Workspace</b>	Separated from human workspace.	Can be shared with people.
<b>Footprint</b>	Large	Small
<b>Flexibility</b>	No. Fixed to one location and works on dedicated task.	Yes. Can be moved between locations during the day to work on different tasks. Built-in camera and Landmark positioning enable quick relocation.
<b>Programming</b>	Difficult. Requires skill and training.	Easy. Can be done with minimal training.
<b>Setup</b>	Requires advanced skills and is time-consuming.	Quick and easy.
<b>Application</b>	Fit for mass production at high speeds.	Fit for high-mix, low-volume production at a speed comparable to human workers. Can be used at high speeds with safety measures.
<b>Cycle Time (Pick &amp; Place)</b>	Down to seconds	Over 5 seconds
<b>Speed of Process (Path)</b>	Below 8.2 m/s	Below 1.4 m/s
<b>Repeatability</b>	+/- 0.02 mm	+/- 0.05 mm
<b>Environment</b>	IP requirements above IP54	IP54 (robot arm), IP32 (control box)
<b>Process Complexity</b>	Can be complex	Should be simple

# Technical Data

## TM5



TM5-700



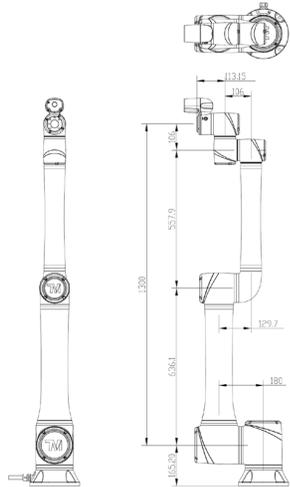
TM5-900

TM5 Specifications				
Model	TM5-700	TM5-900	TM5X-700	TM5X-900
Weight	22.1kg	22.6kg	21.8kg	22.3kg
Maximum Payload	6kg	4kg	6kg	4kg
Reach	700mm	900mm	700mm	900mm
Typical Speed	1.1m/s	1.4m/s	1.1m/s	1.4m/s
Joint ranges	J1,J6	+/- 270°	+/- 270°	+/- 360°
	J2,J4,J5	+/- 180°	+/- 180°	+/- 360°
	J3	+/- 155°		
Speed	J1~J3	180°/s		
	J4~J6	225°/s		
Repeatability	+/- 0.05 mm			
Degrees of freedom	6 rotating joints			
I/O ports		Digital in	Digital out	Analog in
	Control Box	16	16	2
	Tool	4	4	1
		Analog out		0
I/O power supply	24V 2.0A for control box and 24V 1.5A for tool			
IP classification	IP54 (Robot Arm); IP32 (Control Box)			
Power consumption	Typical 220 watts			
Temperature	The robot can work in a temperature range of 0-50°C			
Power supply	100-240 VAC, 50-60 Hz or 22-60 VDC			
I/O Interface	3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0			
Communication	RS232, Ethernet, Modbus TCP/RTU (master & slave), Optional EtherNet/IP or PROFINET			
Programming Environment	TMflow, flowchart based			
Certification	CE, SEMI S2 (optional)			
Robot Vision				
Eye in Hand (Built in)	1.2M/5M pixels, color camera		N/A	
Eye to Hand (Optional)	Support Maximum 2 GigE cameras			

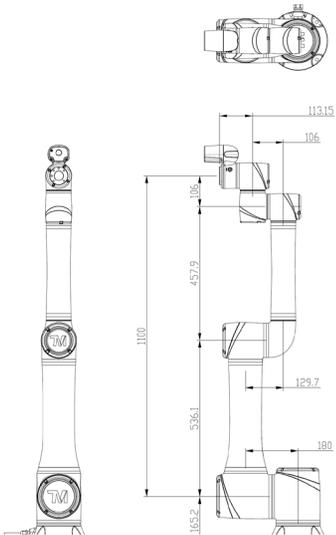
1. No-camera version available on request.

# Technical Data

## TM12/14



**TM12**



**TM14**

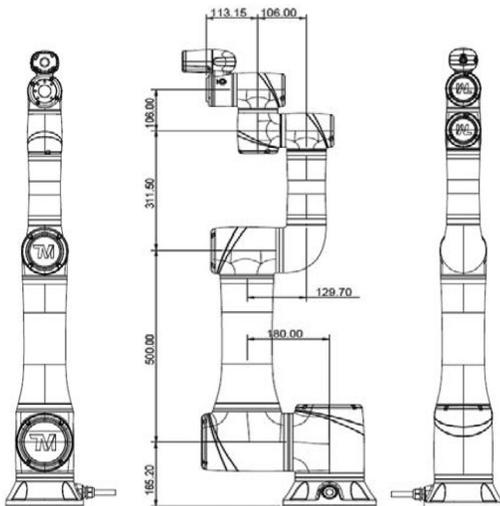
### TM12/14 Specifications

Model	TM14	TM12	TM14X	TM12X	
Weight	32.6Kg	33.3Kg	32.3Kg	33Kg	
Maximum Payload	14kg	12kg	14kg	12kg	
Reach	1100mm	1300mm	1100mm	1300mm	
Typical Speed	1.1m/s	1.3m/s	1.1m/s	1.3m/s	
Joint ranges	J1,J6	+/- 270°	+/- 270°	+/- 360°	+/- 360°
	J2,J4,J5	+/- 180°	+/- 180°	+/- 360°	+/- 360°
	J3	+/- 163°	+/- 166°	+/- 163°	+/- 166°
Speed	J1~J2	120°/s			
	J3	180°/s			
	J4~J5	150°/s	180°/s	150°/s	180°/s
	J6	180°/s			
Repeatability	+/- 0.1 mm				
Degrees of freedom	6 rotating joints				
I/O ports		<b>Digital in</b>	<b>Digital out</b>	<b>Analog in</b>	<b>Analog out</b>
	<b>Control Box</b>	16	16	2	1
	<b>Tool</b>	4	4	1	0
I/O power supply	24V 2.0A for control box and 24V 1.5A for tool				
IP classification	IP54 (Robot Arm); IP32 (Control Box)				
Power consumption	Typical 220 watts				
Temperature	The robot can work in a temperature range of 0-50°C				
Power supply	100-240 VAC, 50-60 Hz or 22-60 VDC				
I/O Interface	3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0				
Communication	RS232, Ethernet, Modbus TCP/RTU (master & slave), Optional EtherNet/IP or PROFINET				
Programming Environment	TMflow, flowchart based				
Certification	CE, SEMI S2 (optional)				
Robot Vision					
Eye in Hand (Built in)	1.2M/5M pixels, color camera		N/A		
Eye to Hand (Optional)	Support Maximum 2 GigE cameras				

1. No-camera version available on request.

# Technical Data

## TM16



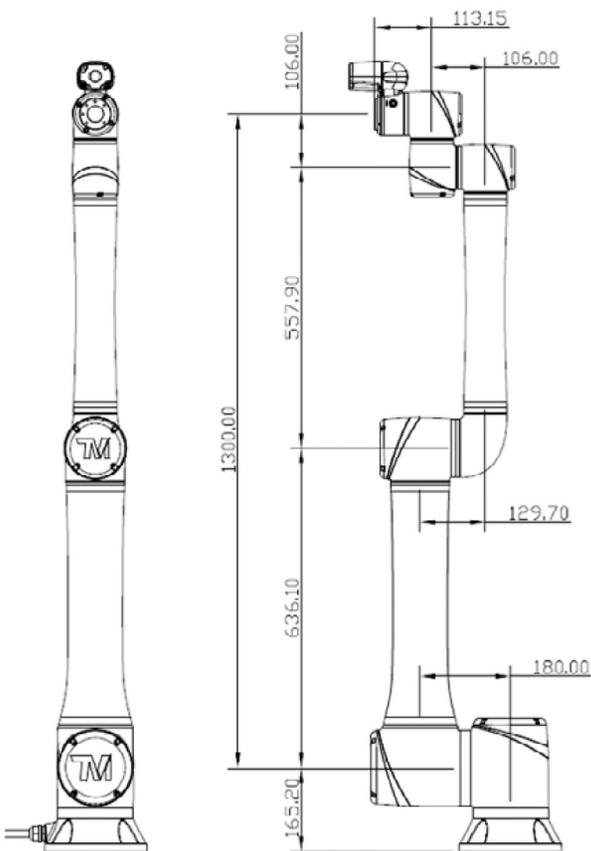
TM16

TM16 Specifications					
Product Name	TM16		TM16X		
Power Source	AC	DC	AC	DC	
Weight (kg)	32		32		
Controller Weight (kg)	14.1		14.1		
Max Payload (kg)	16				
Reach (mm)	900				
Mounting	Wall, Table, Ceiling				
Typical Speed (m/s)	1.1				
Joint Ranges	Joint 1	+/- 270°		+/- 360°	
	Joint 2,4,5	+/- 180°		+/- 360°	
	Joint 3	+/- 155°			
	Joint 6	+/- 270°		+/- 360°	
Joint Speeds	Joint 1,2	120°/s			
	Joint 3-6	180°/s			
Repeatability (mm)	+/- 0.1 mm				
Ingress Protection	IP 54 (robot arm), IP 32 (control box), IP 40 (robot stick)				
Cleanroom Class	ISO Class 3				
Operating Temperature & Humidity	0 to 50°C, 85% max (with no condensation)				
Storage Temperature & Humidity	-20 to 60°C, 75% max (with no condensation)				
Operating & Storage Environment	No corrosive gases or exposure to water-soluble cutting oil				
Motor Power Supply	110 to 240 VAC 50/60 HZ	22 to 60 VDC	110 to 240 VAC 50/60 HZ	22 to 60 VDC	
Robot Arm Cable Length	3 m	1.5 m	3 m	1.5 m	
I/O ports		Digital in	Digital out	Analog in	Analog out
	Control Box	16	16	2	1
	Tool Conn.	4	4	1	0
Communication	RS232, Ethernet, Modbus TCP/RTU (master & slave), PROFINET (optional), EtherNet/IP (optional)				
I/O Power Supply	24 VDC 2.0 A(control box), 24 VDC 1.5A(tool)				
Programming Environment	TMFlow, flowchart based				
Integrated Camera Available	5M Pixels, color	5M Pixels, color	None	None	
SEMI S2 Certification <sup>2</sup> Available	No	Yes	No	No	

<sup>1</sup> If water-soluble cutting oil is present, use a protective sleeve to prevent damage to the robot housing.

<sup>2</sup> SEMI (Semiconductor Equipment and Materials International) is the central global network of manufacturers of micro and nano electronics that issues safety guidelines. SEMI S2 is the most well-known standard in semiconductor manufacturing equipment for Environmental, Health, and Safety (EHS).

# Technical Data TM20



TM20

## TM20 Specifications

Product Name	TM20		TM20X	
Power Source	AC	DC	AC	DC
Weight (kg)	33		33	
Controller Weight (kg)	14.1		14.1	
Max Payload (kg)	20			
Reach (mm)	1300			
Mounting	Wall, Table, Ceiling			
Typical Speed (m/s)	1.3			
Joint Ranges	Joint 1	+/- 270°	+/- 360°	
	Joint 2,4,5	+/- 180°	+/- 360°	
	Joint 3	+/- 166°		
	Joint 6	+/- 270°	+/- 360°	
Joint Speeds	Joint 1,2	90°/s		
	Joint 3	120°/s		
	Joint 4	150°/s		
	Joint 5	180°/s		
	Joint 6	225°/s		
Repeatability (mm)	+/- 0.1 mm			
Ingress Protection	IP 54 (robot arm), IP 32 (control box), IP 40 (robot stick)			
Cleanroom Class	ISO Class 3			
Operating Temperature & Humidity	0 to 50°C, 85% max (with no condensation)			
Storage Temperature & Humidity	-20 to 60°C, 75% max (with no condensation)			
Operating & Storage Environment	No exposure to corrosive gases or liquids			
Motor Power Supply	110 to 240 VAC 50/60 HZ	24 to 60 VDC	110 to 240 VAC 50/60 HZ	24 to 60 VDC
Robot Arm Cable Length	3 m or 12 m	1.5 m	3 m or 12 m	1.5 m
I/O ports		<b>Digital in</b>	<b>Digital out</b>	<b>Analog in</b>
	<b>Control Box</b>	16	16	2
	<b>Tool Conn.</b>	4	4	1
I/O Interface	COM: 3, HEMI: 1, LAN: 3, USB2.0: 4, USB3.0: 2			
Communication	RS232, Ethernet, Modbus TCP/RTU (master & slave), PROFINET (optional), EtherNet/IP (optional)			
I/O Power Supply	24 VDC 2.0 A(control box), 24 VDC 1.5A(tool)			
Programming Environment	TMFlow, flowchart based			
Integrated Camera Available	5M Pixels, color	5M Pixels, color	None	None
SEMI S2 Certification <sup>2</sup> Available	No	Yes	No	No

<sup>1</sup>SEMI (Semiconductor Equipment and Materials International) is the central global network of manufacturers of micro and nano electronics that issues safety guidelines. SEMI S2 is the most well-known standard in semiconductor manufacturing equipment for Environmental, Health, and Safety (EHS).

# Global Network

For decades, Omron's safety services have been the partner of choice of global brands and machine manufactures in automotive, food and beverage, consumer electronics and cosmetics industries. Our expertise in industrial, mobile, and collaborative robotics combined with 85+ years of experience in industrial automation gives us unparalleled expertise in safety.

## Risk Assessment Service

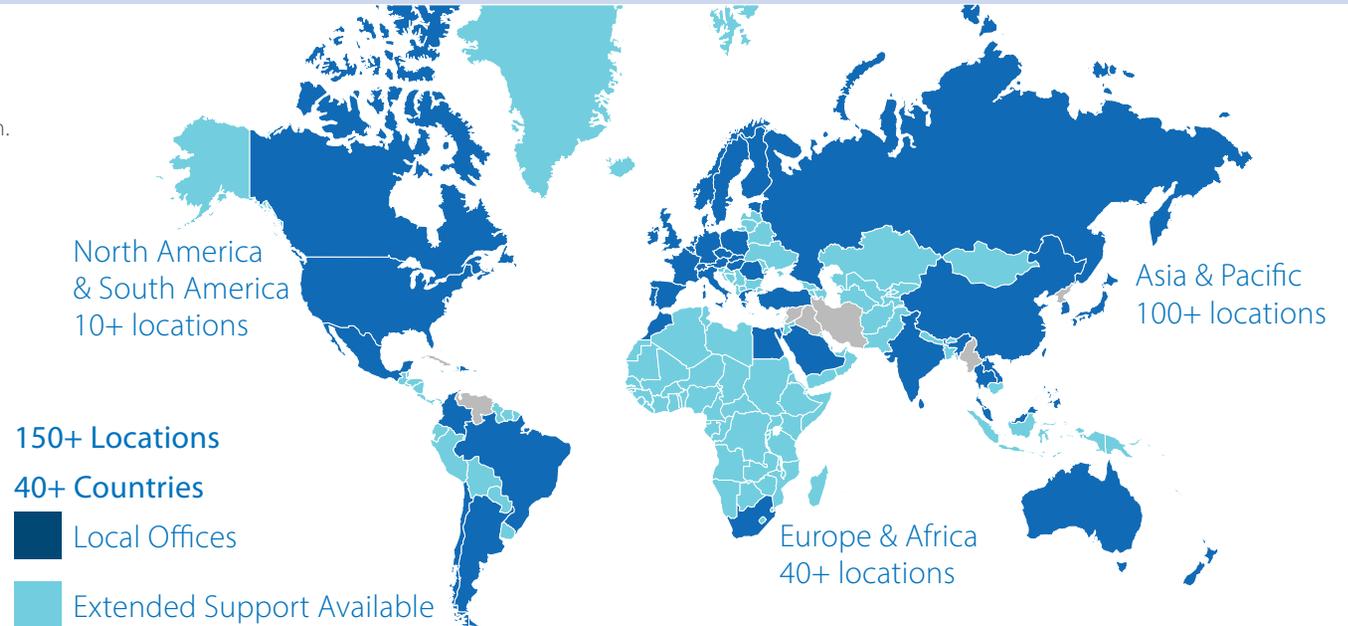
Omron's Risk Assessment Service helps customers mitigate potential safety hazards before deploying a robotics solution. Our functional safety engineers bring unrivaled expertise to work with customers onsite, to identify relevant standards and requirements for human-machine interaction.

### We offer:

- Support with process analysis, identification of application use cases, tasks, and potential collision points.
- Risk, compliance, and conformity assessment according to latest industry standards.
- Risk reduction strategies with a focus on shared human-robot workspace and end-effector design.

## Training

We provide strategic training programs On-demand (Virtual) or in person to customers get the most out of your new robot systems. Our courses include programming of collaborative robot applications and it is applied to all level of users, from beginners to advanced.



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