Programmable multi-axis controller

CK3M

Control with high precision
Maximize your machine’s performance

Performing precise linear motor drive control and nanoscale positioning, the PMAC (Programmable Multi Axis Controller) has been appreciated by manufacturers of semiconductor manufacturing equipment and other leading-edge equipment. Omron now offers a next generation motion controller CK3M that packs PMAC’s superior motion control capability, multi-vendor connectivity, and flexible development capability into its compact design. The CK3M removes constraints and barriers and maximizes your machine’s capabilities.

Rapid
[High-precision control]
Ultra-fast calculation takes high-speed, high-precision control to a new dimension. Its overwhelming calculation speed boosts your machine’s precision.

Ultra-high-speed synchronous control
The CK3M delivers industry-leading*1 output speeds: 50 μs/5 axes. Ultra-high-speed feedback control enables precise path control in precision machining.

*1 Omron survey as of March 2018

Fast servo cycle time for precise path control
The CK3M receives a feedback value and generates a command value to adjust to the target value at a high speed, providing more precise path control.

Flexible
[System configuration made simple]
You can freely use multi-vendor actuators and encoders, which maximizes your machine’s performance.

Advanced encoders
The capability to accept the A/B phase signals and parallel binary signals from serial data interfaces enables high-precision positioning using advanced encoders.

Various actuators
Axes can be controlled by analog commands (DAC, and direct PWM*2). The CK3M can interface with virtually any type of motor including voice coil motors and linear motors to provide precise machine operation.

*2 Direct PWM will be available soon.

Capable
[Continuous development through customization]
The PMAC architecture with flexible function development capability helps you realize your ideas such as incorporation of your own algorithms.

Programming flexibility
G-Code, ANSI C, or original programming language allows you to create complex and advanced algorithms.

In addition to customizing standard G-Code functions, you can also incorporate your own G-Code functions.

Custom servo algorithms
Full closed loop control by servo drives can be incorporated into the controller. You can customize machine control such as vibration suppression optimized for the machine mechanism.

Easy
[Easy to use like a PLC]
Thanks to its compact design, the CK3M is easy to install in the control panel. Tool-free unit connection and DIN track mounting make both installation and replacement surprisingly efficient.

Modular design
The modular design allows you to freely combine the CK3M with expansion units*3 to enable a variety of applications.

*3 Up to two axial interface units can be mounted to the CK3M-CPU1.*

Tool-free connection & compact size
Units can be easily connected without tools. Its compact design*4 reduces control panel size.

DIN track mounting
Units can be easily mounted on a DIN track in a control system.

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High-precision control of precision mechanisms

Used in conjunction with advanced actuators, encoders, and precision mechanisms, the CK3M enables a wide variety of applications where both speed and accuracy are required.

**Rapid**
High-precision control

**Flexible**
Modular design to optimize system configuration

**Mechatronics**

**Capable**
Continuous development through customization

**Easy**
Easy to use like a PLC

**Application**

**Processing/pressing machines**
High-speed, high-precision processing for electro-discharge machines, water jet machines, laser processing machines, grinders, and precision pressing machines

**Semiconductor/FPD manufacturing/inspection machines**
Extremely precise motion for exposure machines, linear coaters, dispensers, and wafer inspection machines

**Robots**
Complex mechanical control for machines using customized robots
Integrated development environment (IDE)

**Power PMAC IDE**

The Power PMAC IDE is an integrated development environment based on Microsoft® Visual Studio® that development engineers use as a development platform around the world. This IDE integrates motion programming for PMAC, motor setup and tuning, debugging, and troubleshooting. Lightweight, sophisticated GUI provides intuitive user operations, which helps you improve application development productivity.

**Microsoft® Visual Studio® based integrated development environment**

Assignment settings for CPU, hardware, EtherCAT®, coordinate systems, and motors can be accessed from one screen.

**ANSI C or original programming language**

In addition to programming in ANSI C and C-language like original programming language, G-Code can be used to write subroutines for G-Code actions.

- **Easy tuning**
  
  Autotuning facilitates tuning of motors. You can fine tune motors through intuitive operations.

- **Simple setting**
  
  Just follow the workflow to set up motors.

- **Troubleshooting**
  
  Possible solutions to your problems are suggested.

- **Debugger**
  
  It provides the Microsoft® Visual Studio® style debugger for Script PLC programs and C background programs.

**IP Protection**

IP Protection allows engineers to protect their intellectual property by encrypting script programs

An engineer can encrypt the script programs per file and pass the project on to another engineer. The engineer who takes the project can add their own logic but cannot list or view the code encrypted by another engineer. The encryption is three-level password protected: OEM builders, independent integrators, and users can share a project securely and flexibly.

**Specifications**

| Software | Power PMAC IDE | Modbus TCP | Industrial switching hub | NB/NA* Programmable Terminal | NJ/NX/NY Machine Automation Controller | EtherCAT®
---|---|---|---|---|---|---

**Three-level IP Protection**

User

Add own logic

Integrator

Add own logic and password protects

OEM builder B

Add own logic and password protects

OEM builder A

Add own logic and password protects

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*Will be available soon
PMAC Series family

- Standard Models

CPU Units

<table>
<thead>
<tr>
<th>Product name</th>
<th>Memory capacity</th>
<th>EtherCAT® port</th>
<th>Max. no. of controlled axes via EtherCAT® port</th>
<th>Expansion</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>CK3M-CPU1</td>
<td>RAM: 1 GB</td>
<td>None</td>
<td>0</td>
<td>0</td>
<td>CK3M-CPU11</td>
</tr>
<tr>
<td>CPU Unit*</td>
<td>Built-in flash memory: 1 GB</td>
<td>EtherCAT®: 1 port (DC sync)</td>
<td>4</td>
<td>+ Expansion units can be connected</td>
<td>CK3M-CPU111</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>CK3M-CPU121</td>
</tr>
</tbody>
</table>

Axial Interface Units

<table>
<thead>
<tr>
<th>Axial Interface Unit</th>
<th>Amplifier interface</th>
<th>Pulse output</th>
<th>Encoder interface</th>
<th>Output type</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>for CK3M-CPU1</td>
<td>DA output (Filtered PWM)</td>
<td>Pulse output method: Pulse + direction or phase difference</td>
<td>Pulse encoder</td>
<td>NPN type</td>
<td>CK3W-AX1414N</td>
</tr>
<tr>
<td></td>
<td>DA output (True DAC)</td>
<td></td>
<td>Serial encoder</td>
<td>PNP type</td>
<td>CK3W-AX1515N</td>
</tr>
<tr>
<td></td>
<td>DA output (Filtered PWM)</td>
<td></td>
<td></td>
<td></td>
<td>CK3W-AX1414P</td>
</tr>
<tr>
<td></td>
<td>DA output (True DAC)</td>
<td></td>
<td></td>
<td></td>
<td>CK3W-AX1515P</td>
</tr>
</tbody>
</table>

Power Supply Unit

<table>
<thead>
<tr>
<th>Power Supply Unit for CK3M-CPU1</th>
<th>Specifications</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Rated output voltage: 5 VDC / 24 VDC, maximum output current: 8 A (5 VDC)</td>
<td>CK3W-PD048</td>
</tr>
</tbody>
</table>

* One End Cover is provided with the CK3M-CPU1 CPU Unit. The CK3W-TER11 End Cover for CK3M-CPU1 is sold separately if required.

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• The product photographs and figures that are used in this catalog may vary somewhat from the actual products.
• PMAC is an abbreviation for Programmable Multi Axis Controller.
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Note: Do not use this document to operate the Unit.