New General-purpose Incremental Rotary Encoder

- A wide operating voltage range of 5 to 24 VDC (Open-collector Models).
- Resolution of 2,000 pulses/revolution in 40-mm housing.
- Phase Z can be adjusted with ease using the origin indicating function.
- A large load of 30 N in the radial direction and 20 N in the thrust direction is permitted.
- The load short-circuit and reversed connection protecting circuit assures highly reliable operation (except for line-driver outputs).

<READ AND UNDERSTAND THIS CATALOG>

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

Ordering Information

<table>
<thead>
<tr>
<th>Power supply voltage</th>
<th>Output configuration</th>
<th>Resolution (P/R)</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 to 24 VDC</td>
<td>NPN open-collector output</td>
<td>10/20/30/40/50/60/100/200/300/360/400/500/600/720/800/1,000/1,024/1,200/1,500/1,800/2,000</td>
<td>E6B2-CWZ6C</td>
</tr>
<tr>
<td>12 to 24 VDC</td>
<td>PNP open-collector output</td>
<td>100/200/360/500/600/1,000/2,000</td>
<td>E6B2-CWZ5B</td>
</tr>
<tr>
<td>5 to 12 VDC</td>
<td>Voltage output</td>
<td>10/20/30/40/50/60/100/200/300/360/400/500/600/1,000/1,200/1,500/1,800/2,000</td>
<td>E6B2-CWZ3E</td>
</tr>
<tr>
<td>5 VDC</td>
<td>Line driver output</td>
<td>10/20/30/40/50/60/100/200/300/360/400/500/600/1,000/1,024/1,200/1,500/1,800/2,000</td>
<td>E6B2-CWZ1X</td>
</tr>
</tbody>
</table>

Note: When ordering, specify the resolution in addition to the model number (example: E6B2-CWZ6C 100P/R).

Accessories (Order Separately)

<table>
<thead>
<tr>
<th>Name</th>
<th>Model</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Coupling</td>
<td>E69-C06B</td>
<td>Provided with the product.</td>
</tr>
<tr>
<td></td>
<td>E69-C66B</td>
<td>Different end diameter</td>
</tr>
<tr>
<td></td>
<td>E69-C610B</td>
<td>Different end diameter</td>
</tr>
<tr>
<td></td>
<td>E69-C06M</td>
<td>Metal construction</td>
</tr>
<tr>
<td>Flange</td>
<td>E69-FBA</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>E69-FBA02</td>
<td>E69-2 Servo Mounting Bracket provided.</td>
</tr>
<tr>
<td>Servo Mounting Bracket</td>
<td>E69-2</td>
<td>—</td>
</tr>
</tbody>
</table>

Application Example

Filling Control
Specifications

### Ratings/Characteristics

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Power supply voltage</strong></td>
<td>5 V DC –5% to 24 VDC +15%, Ripple (p-p): 5% max.</td>
<td>12 V DC –10% to 24 VDC +15%, Ripple (p-p): 5% max.</td>
<td>5 V DC –5% to 12 VDC +10%, Ripple (p-p): 5% max.</td>
<td>5 V DC ±5%, Ripple (p-p): 5% max.</td>
</tr>
<tr>
<td><strong>Current consumption</strong></td>
<td>70 mA max.</td>
<td>80 mA max.</td>
<td>130 mA max.</td>
<td></td>
</tr>
<tr>
<td><strong>Resolution (pulses/rotation)</strong></td>
<td>10/20/30/40/50/60/100/200/300/360/400/500/600/720/800/1,000/1,024/1,200/1,500/1,800/2,000 P/R</td>
<td>100/200/360/500/600/1,000/2,000 P/R</td>
<td>10/20/30/40/50/60/100/200/300/360/400/500/600/1,000/1,024/1,200/1,500/1,800/2,000 P/R</td>
<td>10/20/30/40/50/60/100/200/300/360/400/500/600/1,000/1,024/1,200/1,500/1,800/2,000 P/R</td>
</tr>
<tr>
<td><strong>Output phases</strong></td>
<td>A, B, and Z</td>
<td>A, A, B, B, Z, Z</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Output configuration</strong></td>
<td>NPN open-collector output</td>
<td>PNP open-collector output</td>
<td>Voltage output (NPN output)</td>
<td>Line driver output (See note 2.)</td>
</tr>
<tr>
<td><strong>Output capacity</strong></td>
<td>Applied voltage: 30 V DC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA)</td>
<td>Applied voltage: 30 V DC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)</td>
<td>Output resistance: 2 kΩ. Sink current: 20 mA max. Residual voltage: 0.4 V max. (at sink current of 20 mA)</td>
<td>AM26LS31 equivalent Output current: High level = Io = –20 mA Low level = Is = 20 mA Output voltage: High level = Vh = 2.5 V min. Low level = Vl = 0.5 V max.</td>
</tr>
<tr>
<td><strong>Max. response speed</strong></td>
<td>100 kHz</td>
<td>50 kHz</td>
<td>100 kHz</td>
<td>100 kHz</td>
</tr>
<tr>
<td><strong>Phase difference on output</strong></td>
<td>90°±45° between A and B (1/4T±1/8T)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Rise and fall times of output</strong></td>
<td>1 μs max. (Control output voltage: 5 V; load resistance: 1 kΩ; cable length: 2 m)</td>
<td>1 μs max. (Cable length: 2 m; source current: 10 mA max.)</td>
<td>1 μs max. (Cable length: 2 m; sink current: 10 mA max.)</td>
<td>0.1 μs max. (Cable length: 2 m; Io = –20 mA; Is = 20 mA)</td>
</tr>
<tr>
<td><strong>Starting torque</strong></td>
<td>0.98 m N m max.</td>
<td>8</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td><strong>Moment of inertia</strong></td>
<td>1 x 10^-6 kg m^2 max.; 3 x 10^-7 kg m^2 max. at 600 P/R max.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Shaft loading</strong></td>
<td>Radial 30 N</td>
<td>20 N</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Max. permissible speed</strong></td>
<td>6,000 r/min.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Protection circuits</strong></td>
<td>Power supply reverse polarity protection. Output load short-circuit protection</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Ambient temperature</strong></td>
<td>Operating: –10°C to 70°C (with no icing) Storage: –25°C to 85°C (with no icing)</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Ambient humidity</strong></td>
<td>Operating/storage: 35% to 85% (with no condensation)</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Insulation resistance</strong></td>
<td>20 MΩ min. (at 500 VDC) between current-carrying parts and case</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Dielectric strength</strong></td>
<td>500 VAC, 50/60 Hz for 1 min between current-carrying parts and case</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Vibration resistance</strong></td>
<td>10 to 500 Hz, 150 m/s^2 or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Shock resistance</strong></td>
<td>1,000 m/s^2 3 times each in X, Y, and Z directions</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Degree of protection</strong></td>
<td>IEC 60529: IP50</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Connection method</strong></td>
<td>Pre-wired Models (standard length: 0.5 m)</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Weight (packed state)</strong></td>
<td>Approx. 10 g</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td><strong>Accessories</strong></td>
<td>Coupling, Hexagonal Wrench, Instruction Manual</td>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
</tbody>
</table>

**Note 1.** An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.

2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable.

3. The maximum electrical response speed is determined by the resolution and maximum response speed as follows:

   \[ \text{Maximum electrical response speed (rpm) = Maximum response speed/resolution x 60} \]

   This means that the E6B2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.
Operation

■ Output Circuits

E6B2-CWZ6C

- 3.3 Ω
- NPN transistor
- 15 mA max. 30 VDC max.
- 5 VDC – 5% to 24 VDC + 15%
- Output signal (Black: phase A, white: phase B, orange: phase Z)

E6B2-CWZ5B

- 3.3 Ω
- PNP transistor
- 35 mA max.
- 5 VDC – 5% to 24 VDC + 15%
- Output signal (Black: phase A, white: phase B, orange: phase Z)

E6B2-CWZ3E

- 2 kΩ
- NPN transistor
- 20 mA max.
- 5 VDC – 5% to 12 VDC + 10%
- Output signal (Black: phase A, white: phase B, orange: phase Z)

E6B2-CWZ1X

- Non-reversed output (Black: phase A, white: phase B, orange: phase Z)
- Reversed output (Black/red: phase A, white/red: phase B, orange/red: phase Z)

■ Connection

Be sure to connect the external terminals correctly or the E6B2-C Rotary Encoder may be damaged.

E6B2-CWZ6C/-CWZ5B/-CWZ3E

<table>
<thead>
<tr>
<th>Color</th>
<th>Terminal</th>
</tr>
</thead>
<tbody>
<tr>
<td>Brown</td>
<td>Power supply (+Vcc)</td>
</tr>
<tr>
<td>Black</td>
<td>Output phase A</td>
</tr>
<tr>
<td>White</td>
<td>Output phase B</td>
</tr>
<tr>
<td>Orange</td>
<td>Output phase Z</td>
</tr>
<tr>
<td>Blue</td>
<td>0 V (common)</td>
</tr>
</tbody>
</table>

E6B2-CWZ1X

<table>
<thead>
<tr>
<th>Color</th>
<th>Terminal</th>
</tr>
</thead>
<tbody>
<tr>
<td>Brown</td>
<td>Power supply (+Vcc)</td>
</tr>
<tr>
<td>Black</td>
<td>Output phase A</td>
</tr>
<tr>
<td>White</td>
<td>Output phase B</td>
</tr>
<tr>
<td>Orange</td>
<td>Output phase Z</td>
</tr>
<tr>
<td>Black/red stripes</td>
<td>Output phase X</td>
</tr>
<tr>
<td>White/red stripes</td>
<td>Output phase B</td>
</tr>
<tr>
<td>Orange/red stripes</td>
<td>Output phase Z</td>
</tr>
<tr>
<td>Blue</td>
<td>0 V (common)</td>
</tr>
</tbody>
</table>

Note: Receiver: AM26LS32 equivalent

Note 1. The shielded cable outer core is not connected to the inner area or the case.
2. The phase-A, phase-B, and phase-Z circuits are all identical.
3. Normally, connect GND to 0 V or to an external ground.
## Timing Charts

### Open-collector Output

**E6B2-CWZ6C**

Direction or resolution: **CW**  
(As viewed from the end of the shaft)

- Phase A: On, Off
- Phase B: On, Off
- Phase Z: On, Off

*Note: Phase A is 1/4±1/8T faster than phase B. The ONs in the above timing chart mean that the output transistor is ON and the OFFs mean that the output transistor OFF.*

**E6B2-CWZ5B**

Direction or resolution: **CW**  
(As viewed from the end of the shaft)

- Phase A: On, Off
- Phase B: On, Off
- Phase Z: On, Off

*Note: Phase A is 1/4±1/8T slower than phase B.*

### Voltage Output

**E6B2-CWZ3E**

Direction or resolution: **CW**  
(As viewed from the end of the shaft)

- Phase A: H, L
- Phase B: H, L
- Phase Z: H, L

*Note: Phase A is 1/4±1/8T faster than phase B.*

**E6B2-CWZ1X**

Direction or resolution: **CW**  
(As viewed from the end of the shaft)

- Phase A: H, L
- Phase B: H, L
- Phase Z: H, L

### Line Driver Output

**E6B2-CWZ3E**

Direction or resolution: **CW**  
(As viewed from the end of the shaft)

- Phase A: H, L
- Phase B: H, L
- Phase Z: H, L

**E6B2-CWZ1X**

Direction or resolution: **CW**  
(As viewed from the end of the shaft)

- Phase A: H, L
- Phase B: H, L
- Phase Z: H, L

*Note: Phase A is 1/4±1/8T slower than phase B.*
Connection Examples

Connection to H7CR-CW Counter

Features of H7CR
- DIN-sized (DIN 48) counter incorporating a prescale function converting the measured value to the actual value.
- Synchronized output and ± indication are available (± area models).
- Models with a general-purpose six-digit display and four-digit display are available.

Connection to K3NR-NB/K3NP-NB Rotary Intelligent Signal Processor

Features of K3NR/K3NP
- Each model incorporates a prescale function with an input range of 50 kHz and the measurement accuracy is 0.006%.
- A variety of outputs, including relay, transistor, BCD, linear, and communications outputs, are available.

Connections with Peripheral Devices

<table>
<thead>
<tr>
<th>Coupling</th>
<th>Specification</th>
<th>Resin, standard</th>
<th>Resin, non-standard opening diameter</th>
<th>Metal</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rotary</td>
<td>Model</td>
<td>Internal shaft diameter (mm)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Encoder</td>
<td></td>
<td>4 (H8), 13, 6 (H8), 15, 8 (H8), 19, 10 (H8), 22</td>
<td>6/8 (H8), 19, 6/10 (H8), 22</td>
<td>6 (H8), 19.1, 10 (H8), 25.4</td>
</tr>
<tr>
<td>E6B2, 6-mm diameter</td>
<td>E6B2-CWZ6C</td>
<td>Black, White, Blue, Brown</td>
<td>CP2 CP1</td>
<td>12 VDC (100 mA)</td>
</tr>
</tbody>
</table>

Note: A: Possible to connect directly in most cases.
B: Possible to connect, but an independent power supply or pull-up resistor will be required.
C: Impossible to connect.
Precautions

WARNING
This product is not designed or rated for ensuring safety of persons. Do not use it for such purposes.

■ Precautions for Safe Use
Incorrect wiring may damage internal circuits.

■ Precautions for Correct Use
Do not use the Encoder under ambient conditions that exceed the ratings.

Input to More than One Counter from Encoder (with Voltage Output)
Use the following formula to obtain the number of counters to be connected to a single E6B2-C Rotary Encoder.

\[
\text{Number of counters (N)} = \frac{R1 (E-V)}{V \times R2}
\]

- **E**: Voltage supplied to Rotary Encoder
- **V**: Minimum input voltage of the counter
- **R2**: Output resistance of the Rotary Encoder
- **R1**: Input resistance of the counter

Origin Indication
It is easy to adjust the position of phase Z with the origin indication function. The following illustration (on the left-hand side) shows the relationship between phase Z and the origin. Set cut face D to the origin as shown in the illustration (on the right-hand side).
**Mounting**

**Mounting Procedure**

1. Insert the shaft into the coupling.

2. Secure the Rotary Encoder.

Refer to the table on the right for the maximum insertion length of the shaft into the coupling.

3. Secure the coupling.

4. Connect the power and I/O lines.

5. Turn ON the Rotary Encoder and check the output.

**Installation**

Be careful not to spray water or oil onto the E6B2-C Rotary Encoder. The E6B2-C Rotary Encoder consists of high-precision components. Handle it with utmost care and do not drop the Rotary Encoder, otherwise malfunctioning may result.

When the E6B2-C Rotary Encoder is used in reversing operation, pay utmost attention to the mounting direction of the E6B2-C Rotary Encoder and the directions of increment and decrement rotation.

To match phase Z of the E6B2-C Rotary Encoder and the origin of the device to be connected to the E6B2-C Rotary Encoder, confirm the phase Z output when connecting the device.

Do not impose an excessive load on the shaft if the shaft is connected to a gear.

If the Rotary Encoder is mounted with screws, the tightening torque must be approximately 0.49 N·m.

Refer to the following illustrations when using a standard coupling.

<table>
<thead>
<tr>
<th>Coupling</th>
<th>Insertion length</th>
</tr>
</thead>
<tbody>
<tr>
<td>E69-C06B</td>
<td>5.5 mm</td>
</tr>
<tr>
<td>E69-C68B</td>
<td>6.8 mm</td>
</tr>
<tr>
<td>E69-C610B</td>
<td>7.1 mm</td>
</tr>
<tr>
<td>E69-C06M</td>
<td>8.5 mm</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Coupling</th>
<th>Tightening torque</th>
</tr>
</thead>
<tbody>
<tr>
<td>E69-C06B</td>
<td>0.25 N·m</td>
</tr>
<tr>
<td>E69-C68B</td>
<td>0.44 N·m</td>
</tr>
<tr>
<td>E69-C610B</td>
<td>0.44 N·m</td>
</tr>
<tr>
<td>E69-C06M</td>
<td>0.7 N·m</td>
</tr>
</tbody>
</table>

Do not secure the coupling and shaft with screws at this stage.

Do not secure the coupling and shaft with screws at this stage.

Do not impose an excessive load on the shaft if the shaft is connected to a gear.

If the eccentricity or declination value exceeds the tolerance, an excessive load imposed on the shaft may damage the Rotary Encoder or shorten the life of the Rotary Encoder.
Mounting
When connecting the shaft of the Rotary Encoder with a chain timing belt or gear, connect the chain timing belt or gear with the shaft via the bearing and coupling as shown in the following illustration.

Do not hit the shaft or coupling with a hammer when inserting the shaft into the coupling. No shock must be applied to the shaft or coupling.
When connecting or disconnecting the coupling, do not bend, press, or pull the coupling excessively.

Bearing Life
The following graph shows the life expectancy (theoretical values) of the bearing with radial and thrust loads imposed on the bearing.

Wiring
If the Rotary Encoder is mounted in a panel, do not pull the cable with more than a force of 29.4 N.

Do not pull the cable of the E6B2-C rotary Encoder after the E6B2-C Rotary Encoder is mounted to a panel. Do not apply any shock to the hollow shaft or the body.

Connections
When extending the cable, select the kind of cable with care, taking the response speed into consideration. The longer the cable is, the more the residual voltage increases due to the resistance of the cable and the capacitance between the wires. As a result, the waveform will be distorted.

OMRON recommends models with a line driver output if the cable needs to be extended.

To reduce inductive noise, the cable must be laid the shortest distance, especially when the signal is input to an IC.
Insert a surge absorber between the power supply terminals if there is any surge.
To reduce noise, the total cable length must be as short as possible.
Incorrect pulses may be generated when the E6B2-C Rotary Encoder is turned ON or OFF. Do not use the connected device for 0.1 s after the E6B2-C Rotary Encoder is turned ON and for 0.1 s before the E6B2-C Rotary Encoder is turned OFF.

Cable Extension
The rise time of each output waveform will increase when the cable is extended. This will affect the phase difference characteristics of phases A and B.
The rise time varies with the resistance of the cable, the kind of cable, and the length of the cable.
The residual output voltage will increase according to the length of the cable.

Measurement example
Power supply voltage: 5 VDC
Load resistance: 1 kΩ
(Residual output voltage was measured at a load current of 35 mA.)
Cable: Dedicated cable

Preventing Miscounting
If the operation of the E6B2-C Rotary Encoder is stopped near a signal rising or falling edge, incorrect pulses may be generated, in which case the E6B2-C Rotary Encoder will miscount. Use an increment-decrement counter to prevent miscounting.

Extension of Line Driver Output
Use twisted-pair cable to extend the line driver cable.
Recommended cable: Tachii Densen’s TKVBS4P-02A
Use an RS-422A receiver.
The twisted-pair wires shown in the following illustration are suitable for RS-422A signal transmission. Normal mode noise can be eliminated by twisting the wires because the generated electrical forces on the lines cancel each other.

Check that the E6B2-C is supplied with 5 VDC when a line driver output is used. There will be an approximately 1 V voltage drop if the cable length is 100 m.
Using a Line Receiver IC
Recommended IC: Texas Instruments

AM26LS32, AM26C32

Others

Input to More than One Counter from Rotary Encoder (with Voltage Output)
Use the following formula to obtain the number of counters to be connected to a single E6B2-C Rotary Encoder.

\[
N = \frac{R_1 (E - V)}{V \cdot R_2}
\]

E: Voltage supplied to Rotary Encoder
V: Minimum input voltage of the counter
R1: Input resistance of the counter
R2: Output resistance of the Rotary Encoder
**Dimensions**

*Note: All units are in millimeters unless otherwise indicated.*

**E6B2-C**

- **Origin of phase Z**: Three, M3 holes
  - Depth: 7 mm

- **Couplings**
  - **E69-C06B (Provided)**
    - Four, M3 hexagon setscrews
    - Material: Glass-reinforced PBT

- **E69-C06M (Order Separately, Different End Diameter)**
  - Four, M3 hexagon setscrews
  - Material: Extra super duralumin

- **Flanges (Order Separately)**
  - **E69-FBA**
    - Four, 3.3 dia. holes
    - Three, 3.5 dia. holes with 6.5 dia. countersunk holes
    - 20.2 dia. hole
    - 30 ± 1 dia.
    - The flange is made of SPCC.
    - t = 3.2
    - Applicable Model: E6B2-C

- **Mounting Bracket**
  - **E69-2**
    - Two, C1
    - 5.5 dia. hole
    - 3.1 ± 0.1
    - (5.1)

**E69-C68B (Order Separately, Different End Diameter)**

- Four, M4 hexagon socket heat setscrews
- Brass bushing
- 6H8 dia.
- 9 dia.
- Material: Glass-reinforced PBT

**E69-C610B (Order Separately, Different End Diameter)**

- Four, 4 hexagon socket heat setscrews
- Brass bushing
- 6H8 dia.
- 22 dia.
- Material: Glass-reinforced PBT

**E69-CWZ6C/5B/3E**

- 5 dia. vinyl-insulated shielded 5-conductor cable (Conductor cross section: 0.2 mm², Insulator diameter: 1.0 mm)
- Standard length: 500 mm

**E69-CWZ1X**

- 5 dia. vinyl-insulated shielded 8-conductor cable (Conductor cross section: 0.2 mm², Insulator diameter: 1.0 mm)
- Standard length: 500 mm

**E69-FBA02**

- Three, 3.5 dia. holes with 6.5 dia. countersunk holes
- The flange is made of SPCC.
- t = 3.2
- Applicable Model: E6B2-C

**Flanges (Order Separately)**

- **E69-FBA**
  - Four, 3.3 dia. holes
  - Three, 3.5 dia. holes with 6.5 dia. countersunk holes
  - 20.2 dia. hole
  - 30 ± 1 dia.
  - The flange is made of SPCC.
  - t = 3.2
  - Applicable Model: E6B2-C
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ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Cat. No. Q085-E1-03A In the interest of product improvement, specifications are subject to change without notice.

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