OMRON

TM Mobile Workstation Manual

TM ROBOT

I628-E-01

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Contents

Revision History Table

Revision	Date	Revised Content
01	October 2018	Original release

1. Product Function and Specification

1.1 Function

TM Mobile Workstation is a convenient tool for users to organize and store TM Robot, control box and other components. Users can move TM Mobile Workstation with TM Robot to different work cells to achieve easy and flexible deployment.

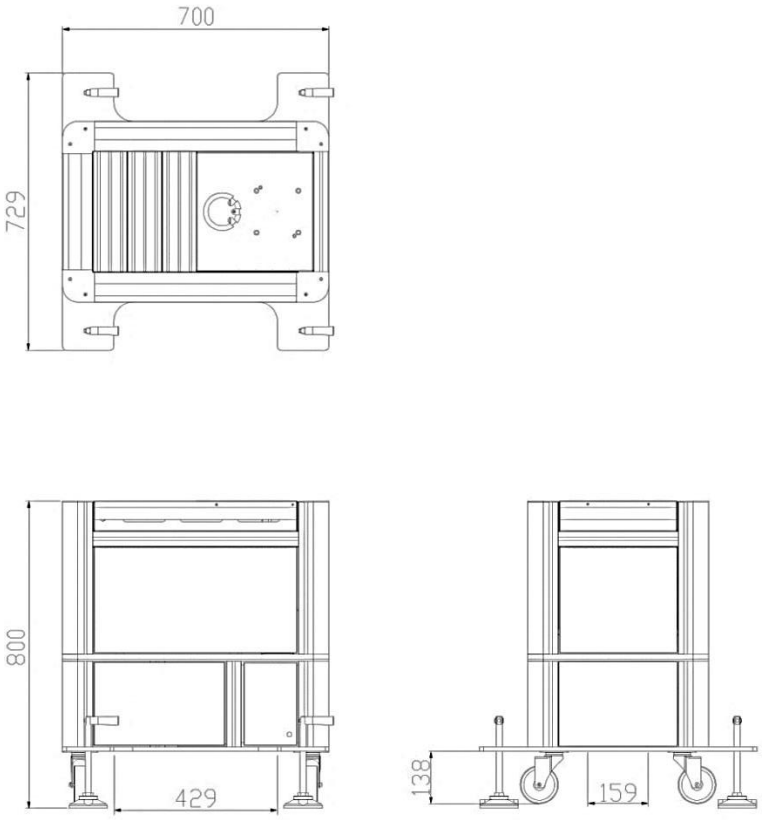
1.2 Specification

Depth	729mm
Width	700mm
Height	800mm
Weight	110kg
Applicable Robot	TM5-700、TM5-900
Max. Recommended Profile(TM5-700/TM5-900):	Up to 80% of max. speed with half max. payload and default acceleration rate (500ms for Time to top speed).

*Max. recommended profile is highly relevant to pose/motion/acceleration, and the status of ground surface.

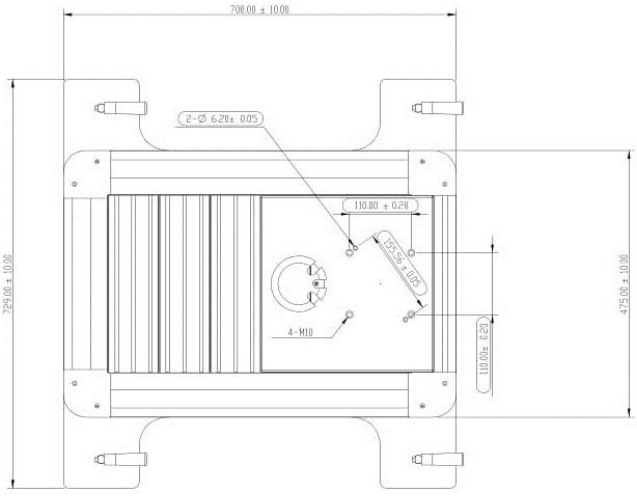
DANGER:
Before installing and using this product, the user must first perform a risk assessments based on the conditions of use. The stability of the center of gravity is highly correlated with robot kinematics (including velocity, acceleration and poses) and environmental factors (including characteristics of the floor surface and structure).
The Corporation clearly specifies the following risks: the product can tip over causing serious injury or death, or damage to itself and other equipment, due to improper risk assessment or test and failure to read and comply with the manuals. Max. recommended profile and related data shall not be considered as a guarantee by the Corporation.

1.3 Three-view Diagram



* The distances have deducted the wheel range.

1.4 Flange Surface



2. Packing List

TM Mobile Workstation has the following items in package.

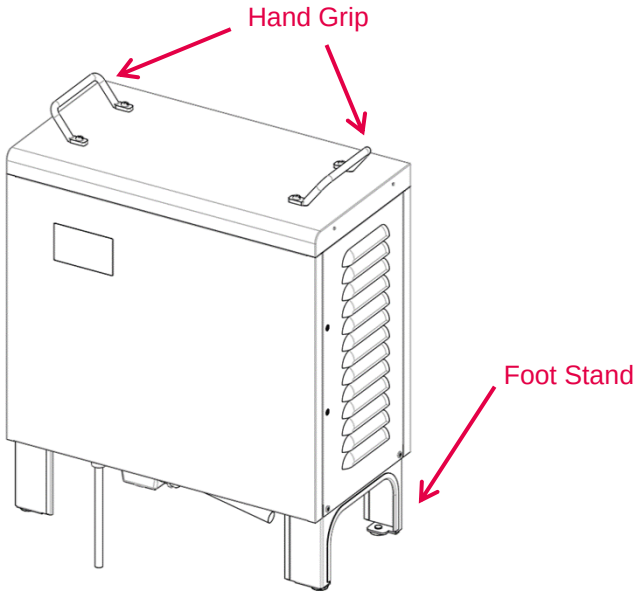
TM Mobile Workstation ×1	Power Cord* ×1	Desktop Cover ×1
		
Bracket(1) ×2	**Bracket(2) ×2**	**Bracket(3) ×2**
		
M4L6 Flat Screw ×6	**M4L6 Screw ×6**	
		

*The specification of power cord is Type B (mainly use in Taiwan, Japan, and American). To be compatible with reginal socket and power cord, we recommend the user uses the power cord which is contained in TM Mobile Workstation to connect control box with TM Mobile Workstation. As for external power, please use the power cord which is contained in TM Robot.

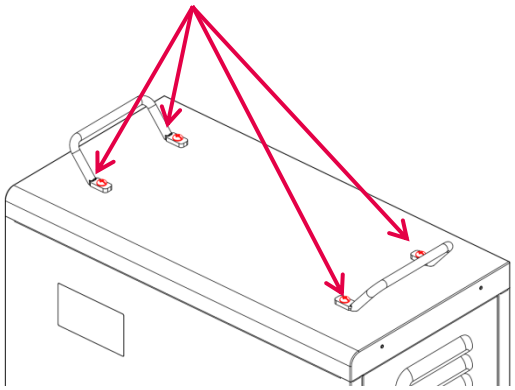
3. Installation

3.1 Control Box Installation

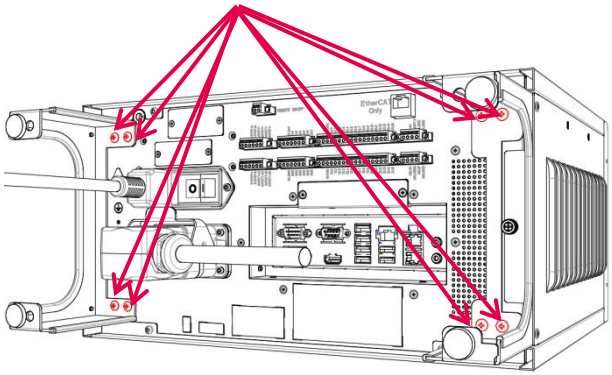
- Remove the hand grips and the foot stands.



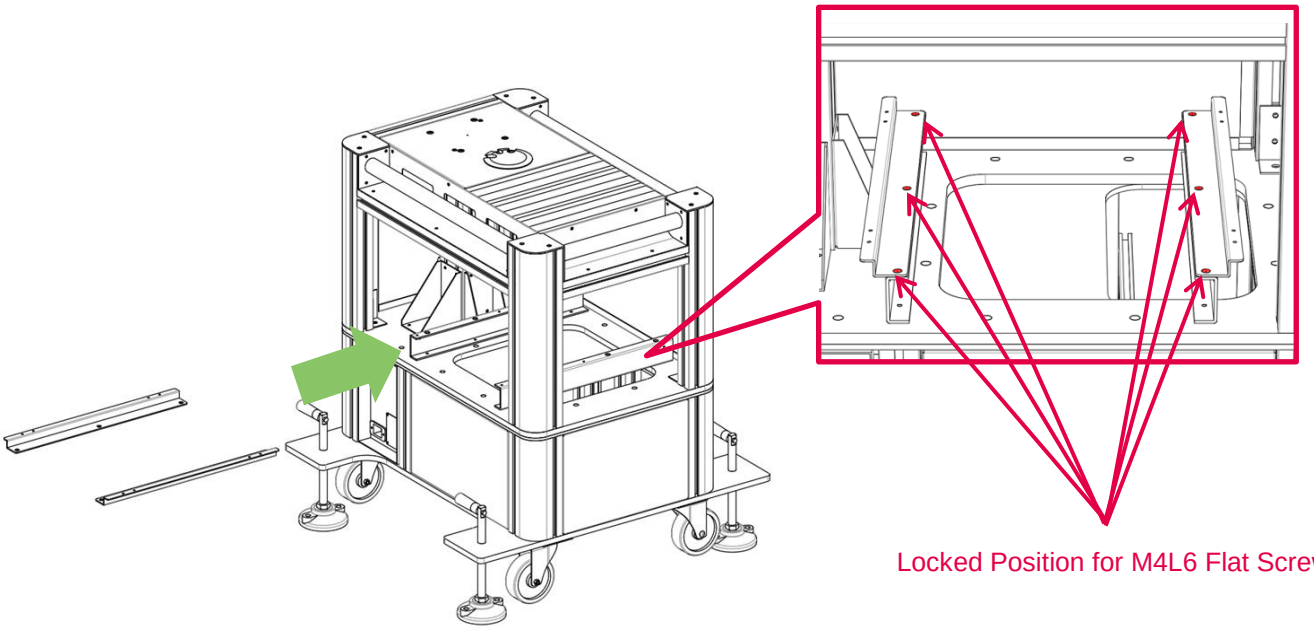
Disassembled Position for Hand Grip



Disassembled Position for Foot Stand

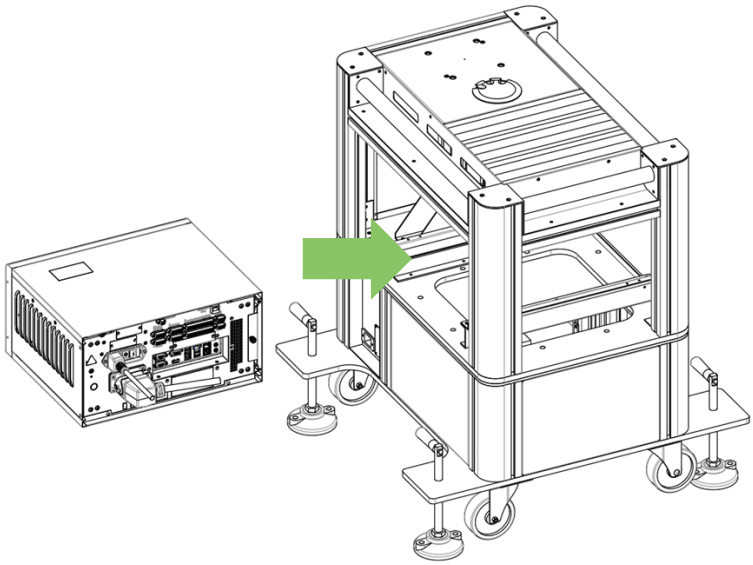


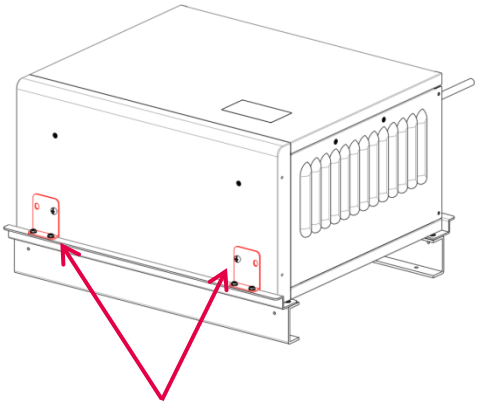
- Put Bracket(1) into TM Mobile Workstation and fix with M4L6 flat screws.



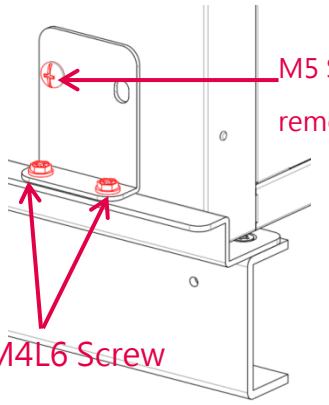
- Put control box into TM Mobile Workstation along Bracket(1), then assemble Bracket(2) and Bracket(3).

(Recommended screw type: take reference for figures shown below.)





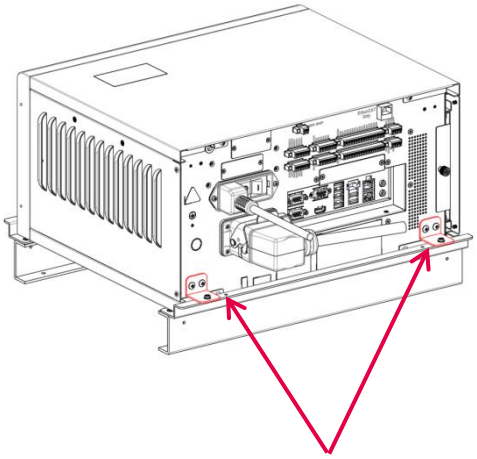
Bracket(2)



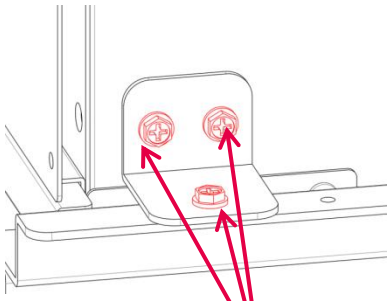
M5 Screws which is

removed from hand grip previously

M4L6 Screw



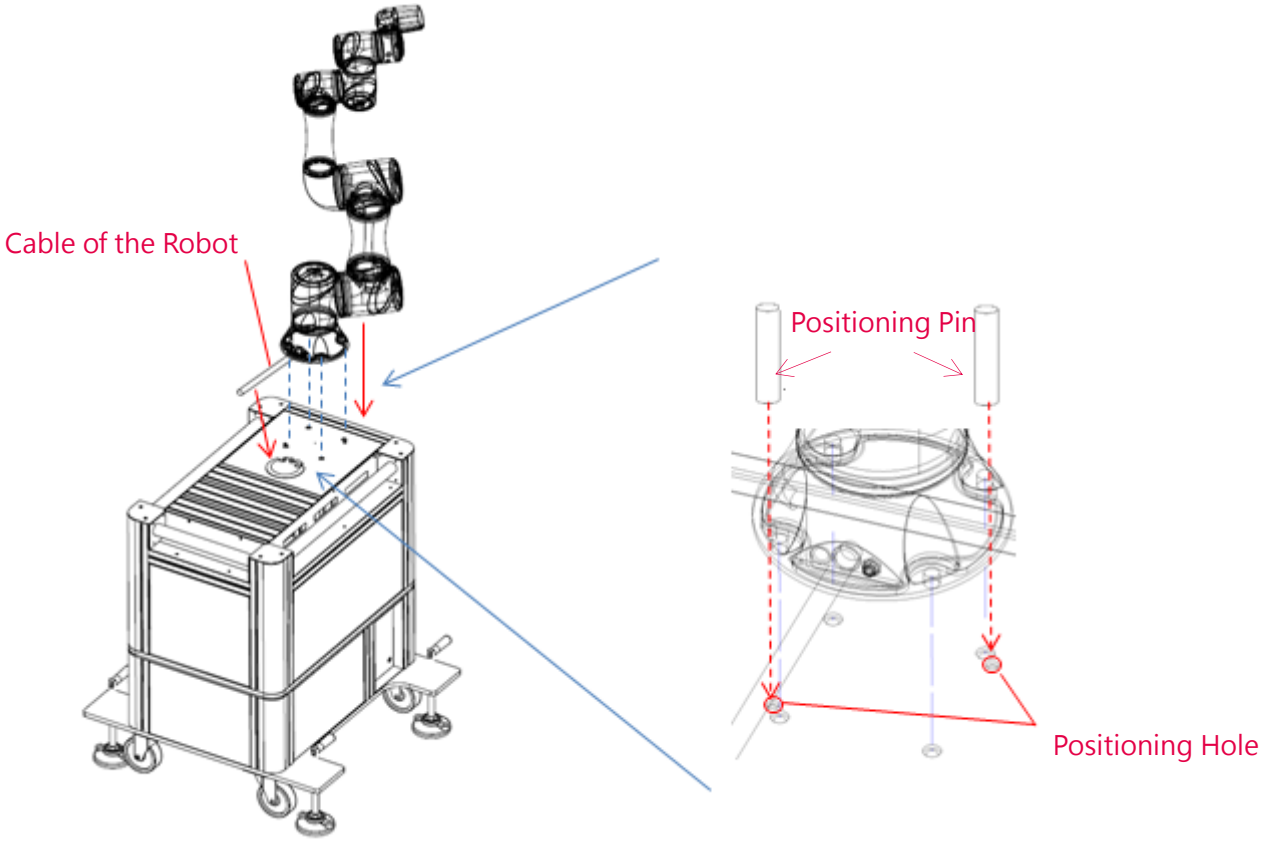
Bracket(3)



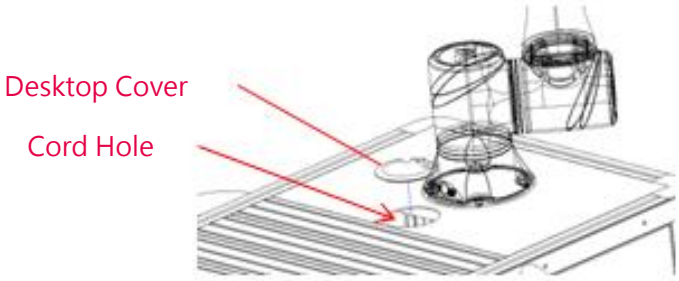
M4L6 Screw

3.2 Robot Arm Installation

- Orient cable of the robot towards the cord hole. Locate TM Robot with positioning pins. Then secure TM robot with M10 screws.

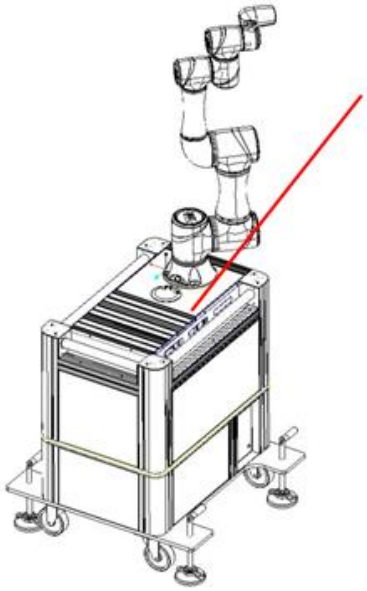


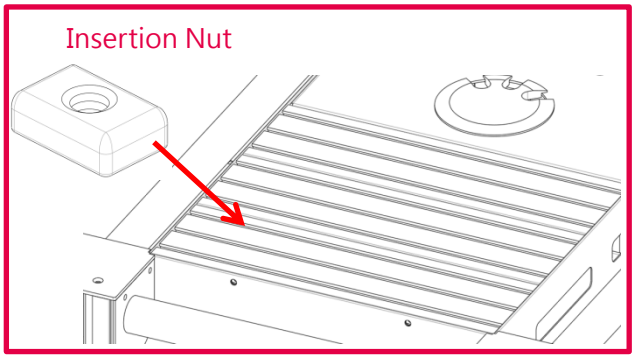
- Pass cable of the robot through the cord hole and connect to control box. Cover the cord hole with desktop cover.



3.3 TM Mobile Workstation Application

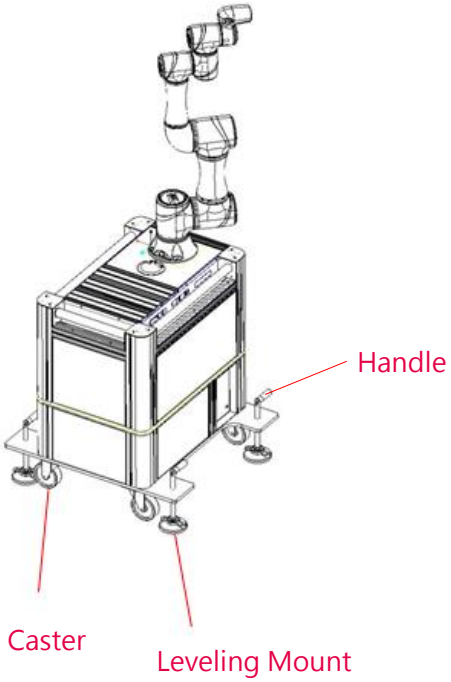
- The user can put insertion nuts (Recommended nut type: 10mmx5mm; M5 or M6) into the slot of the desktop, and uses screws to lock required application on these nuts.





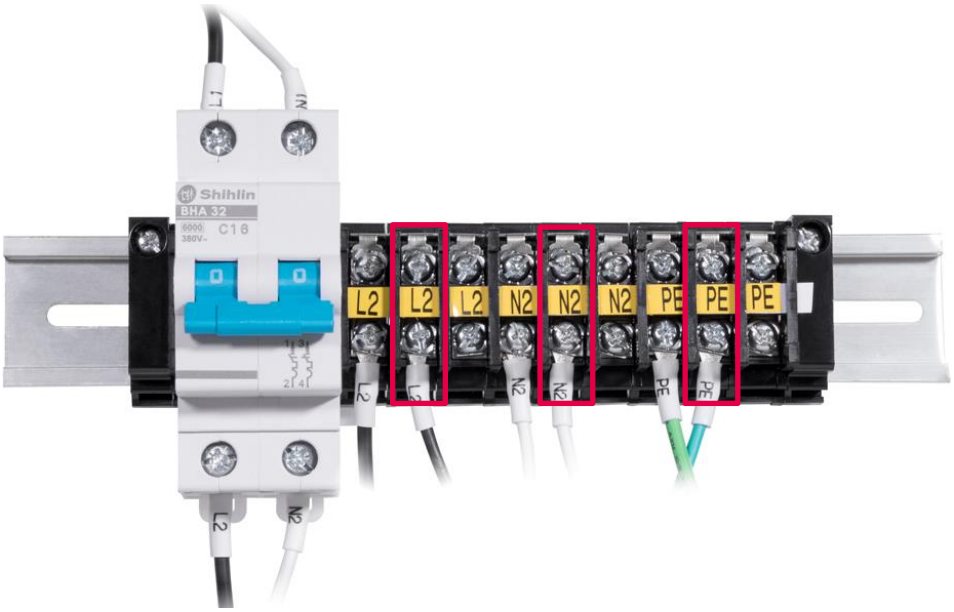
3.4 Casters Setting

- To move the TM Mobile Workstation: Turn the handles counterclockwise. The casters would touch the ground.
- To fix the TM Mobile Workstation: Turn the handles clockwise. The casters would be lifted.

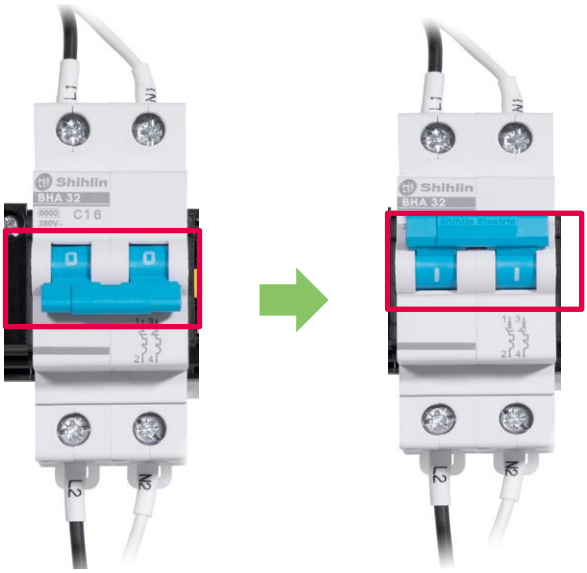


3.5 Terminal Block Wiring

- After shutting down Control Box and turning off the no-fuse breaker, connect L2, N2, PE with the extension cord.



- Turn on the no-fuse breaker.



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