Quick, easy and flexible integration of production line safety

Scalable from large automotive production lines to small parts production lines

- Flexible safety system for large-scale production
- Interlocking between various machines

Quick and easy safety program design

- Reduce time required for design
- Reduce time required for verification

Efficient safety management and maintenance

- Minimize system downtime
- Reduce maintenance work
Manufacturers need flexible systems for high-mix production on a global scale. Safety control requirements make these system designs even more complicated. To help reduce design and maintenance time so that manufacturers can efficiently build flexible systems, we offer the NX Safety Network Controller.

**Safety control for large systems**

**High-speed safety control for mid-size systems**

**NX Safety Network Controller**

- **Communication Control Unit**: NX-CSG320
- **Safety CPU Unit**: NX-SL5500/5700
- **Machine Automation Controller**: NX-102
- **Safety CPU Unit**: NX-SL5500/5700

**Safety I/O Terminal**

- **Input model**: GI-SID1224
- **Output model**: GI-SMD1624

**Automation Software**

- **SYSMAC SE/FE**

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**EtherNet/IP**

EtherNet/IP® is a widely used and vendor-independent industrial Ethernet network that is managed by ODVA.

**EtherCAT**

EtherCAT® is an industrial real-time communication network promoted by EtherCAT Technology Group (ETG).

**Safety over EtherCAT (FSoE)**

Safety over EtherCAT (FSoE) allows a single communication system to be used for both control and safety data.
Flexible safety system for large-scale production

EtherNet/IP for safety across the world

Production systems must meet worldwide standards on account of globalization. CIP Safety is a protocol for transmitting safety data via EtherNet/IP that is adopted by factory automation and robot manufacturers all over the world. Using CIP Safety, you can build globally standardized networks and simplify the global procurement of production systems.

One connection using CIP Safety

Safety systems for industrial robots are gaining popularity. Networks can be easily built with Omron’s NX-CSG Communication Control Unit and NX-SL5 Safety CPU Units which support CIP Safety.

EtherNet/IP brings flexibility

Multiple network ports allow a safety network to be divided into several segments, thereby making it easy to connect the numerous network devices required for large production lines. This creates the flexibility to add or remove devices from existing safety systems.

Safety control between lines: Port 1
Robot control within process: Port 2A, 2B

Fast and fixed response cycle facilitates reconfiguration

The NX-CSG320 Communication Control Unit and NX-SL5 Safety CPU Unit provide safety communications via CIP safety while also enabling local, high-speed safety I/O control. With a local I/O response time as low as 50 ms, the NX-SL5 Safety CPU Unit can be used for applications where a high level of responsiveness is required.

* Calculate the response speed of your system taking the performance of I/O devices into consideration. Refer to the manual for details.

Fastest cycle time: 50 ms
Standardize the safety system network for a large robot system

System configuration

In this example, devices and machines communicate via EtherNet/IP and CIP Safety in this system. Each process includes robots, safety light curtains, emergency stop switches, and other safety components. The NX-CSG and NX-SLS execute safety control programs in each process. CIP Safety is used for safety interlocking between processes and for building a safety control network across the system.

* Understand the connection specifications of devices which are used in the system before creating a network.
Safety Network Controller

Interlocking between various machines

Simple configuration

CIP Safety allows safety devices and standard devices to be mixed on the same network, providing safety interlock control between machines. CIP Safety robots and remote I/O terminals can be easily connected.

Modular processes bring flexibility to line layouts

The NX-CSG320 communication control unit and NX-SL5 Safety CPU Unit exchange interlock signals with other machines while implementing safety control within the machine. Programs for machine control and safety control can be created for each machine. This modularized design helps standardize design and improve design efficiency.

Modular machines with individual CPU units

System configuration

Machine 1 and 3 are processing machines with the control program and safety control program for each machine. Machine 2 is a material handling machine that transports products processed by Machine 1 and 3 to the next process. The NX-CSG320 communication control unit and NX-SL5 Safety CPU Unit are used for all machines, and CIP Safety is used for safety interlocking between machines.

* Understand the connection specifications of devices which are used in the system before creating a network.
Two different networks in a single system

The NX-SL5 Safety CPU Unit connected with the NX102 Machine Automation Controller enables the use of both EtherCAT + FSoE (Safety over EtherCAT) and EtherNet/IP + CIP Safety at the same time. In addition to interlock control within a machine via FSoE, safety interlock between machines can be implemented using CIP Safety.

Integrated safety into high-speed machine control

The NX-SL5 Safety CPU Unit combination with the NX102 Machine Automation Controller, provides both safety control and machine control with fast cycle times. By mounting NX-SL5 Safety CPU Unit and safety I/O units to the NX102 and by connecting the servo drives via FSoE on EtherCAT, you can configure a simple motion and safety control system using high-speed networks.

Line safety control and fast machine control at the same time

System configuration

The NX102 Machine Automation Controller and NX-SL5 Safety CPU Unit are used in Machine 1 and 2 to build a system with safety network and real-time control capabilities using EtherCAT. The machine status is reported to the host system and displayed on the HMI connected on the same network.

* Understand the connection specifications of devices which are used in the system before creating a network.
The Automation Software Sysmac Studio provides various functionalities to reduce time required for production system design and safety program verification.

**Design**

Reduce time required for production system design

**Automatic Programming**

Create a truth table using input, output, and stop conditions of safety devices to automatically produce a safety program for a simple machine.

* Programs created by Automatic Programming will not guarantee functional safety.

**User-defined Function Block (FB)**

Programs can be easily converted into a user-defined function block (FB), and help files can be attached to describe input and output conditions as well as the functionality of the program within the function block. Different security levels can be set to protect the FB from viewing and unauthorized modifications.

* User-defined FBs can be used as modular software components according to the hardware configuration. They help standardize programs and maintain the consistency of design quality.
Offline Simulation

Programs can be simulated on your PC, Sysmac Studio allows verification of programs without connecting hardware.

Online Functional Test

Online Functional Test enables operation of safety functions to be checked when the NX-SL5 Safety CPU is online with Sysmac Studio. The test results can be output as a report along with the safety signature; the safety signature is displayed on the seven-segment display of the NX-SL5 Safety CPU Unit, and can easily checked if the configuration matches the report after the program has been validated.

* Based on Omron investigation in March 2018.

[Preparation]
Start the Sysmac Studio and go online with the NX-SL5. Register the safety devices to test and set the expected values of each signal.

[Testing]
Operate safety devices by following the instructions on the screen. Check if each device operates correctly and input the check results.

[Tests completed]
The test results are listed after all tests have been completed. The list can be output as a CSV file.

[Printing test results]
The test details, results, and executed date and time can be output as a PDF file. The names of the tester and approver can be added. The safety signature code, which identifies the validated program, is included at the bottom right of the report.
Maintenance without PC

No PC is required for maintenance, which reduces production system maintenance work and minimizes system downtime.

Design
- Hardware/software

Verification
- Safety program/system operation check

Operation
- Maintenance

Safety Data Logging
An SD card containing logging settings is used for Safety Data Logging. When start trigger conditions are met, the specified device variables and exposed variables can be logged in a chronological order and output to the memory card. This function helps to quickly identify the cause of a sudden stoppage of the system and determine preventive measures.

Safety Unit Restore
Programs and settings can be stored on an SD card inserted into the communication control unit. When the safety CPU unit is replaced, the stored programs and settings can be easily copied to a new unit using the SD card.

ACR (Automatic Configuration Restart)
When replacing a safety I/O unit, just remove the old unit and mount a new unit. The setting data is automatically downloaded without using software.
# Existing products

Choose a safety controller to suit your application.

<table>
<thead>
<tr>
<th>Product name</th>
<th>Features</th>
<th>Catalog</th>
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</table>
| **NX Safety Controller** | Integration of safety into machine automation enables simple, flexible system configuration  
- Fully integrate safety and standard control in one network by connecting with an NX EtherCAT Coupler Unit  
- Safety CPU unit: Up to 128 safety I/O units  
- Safety input unit: 8 or 4 safety input points per unit  
- 4-channel units can be directly connected with Omron non-contact switches and single-beam sensors  
- Safety output unit: 2 or 4 safety output points per unit  
- Output breaking current of 2.0 A (2-channel units)  
- PL.Copen* Function Blocks for Safety  
- Standard IEC 61131-3 programming | Refer to omron247.com |
| **Safety Network Controller** | Acts as a DeviceNet Safety master and slave and hosts the safety application program  
- NE1A-SCPU01-V1 with built-in 16 safety inputs and 8 safety outputs  
- NE1A-SCPU02 with built-in 40 safety inputs and 8 safety outputs  
- Simplifies safety systems. With safety network master capabilities, up to 32 safety nodes  
- Safety system can be monitored by standard controller via DeviceNet | Refer to omron247.com |
| **Safety Network Controller** | Acts as a DeviceNet Safety master and slave and monitors safety system via EtherNet/IP  
- Connect with Omron PLC via EtherNet/IP for easy maintenance  
- Simplifies safety systems. With safety network master capabilities, up to 32 safety nodes  
- No external devices required for connecting to EtherNet/IP | Refer to omron247.com |
| **Safety Network Controller** | As a standalone controller as well as a DeviceNet Safety slave  
- TÜV-certified templates for safety applications with up to 12 inputs  
- Reusable user-defined safety circuit templates for easy standardization  
- NE0A operating status can be monitored by standard DeviceNet master | Refer to omron247.com |
| **Safety Controller** | Standalone safety controller  
- Easy programming for complex safety control  
- Unique programming software (G9SP Configurator) to support easy design and verification | |

# Related products

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<tr>
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<tr>
<td><strong>Machine Automation Controller</strong></td>
<td>Brings advanced control in miniaturized size</td>
<td>Refer to omron247.com</td>
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